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# Confidence Limits and Intervals

## 3: Various other topics

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SLUO Lectures on Statistics

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1. Likelihood and  $\Delta \ln L$
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# 1 The Likelihood Ratio

Estimate a model parameter  $M$  by maximising the likelihood

In the large  $N$  limit

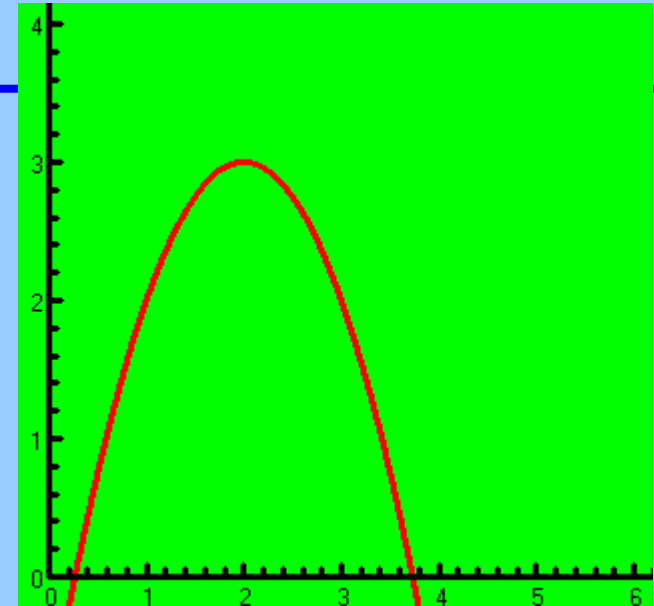
i) This is unbiased

ii) The error is given by

$$\frac{1}{\sigma^2} = -\left\langle \frac{d^2 \ln L}{dM^2} \right\rangle$$

iii)  $\ln L$  is a parabola

$$L = L_{max} - \frac{1}{2} C (M - \hat{M})^2$$



iv) We can approximate

$$C \equiv \left. \frac{-d^2 \ln L}{dM^2} \right|_{M=\hat{M}} = -\left\langle \frac{d^2 \ln L}{dM^2} \right\rangle$$

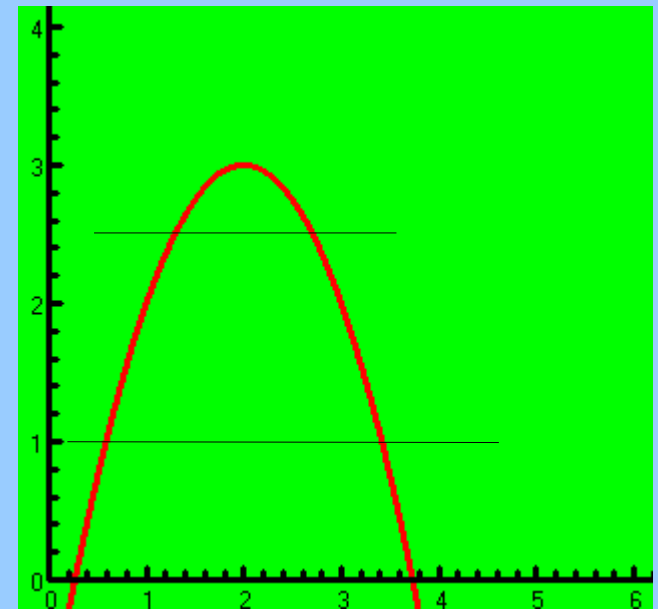
v) Read off  $\sigma$  from  $\Delta \ln L = -1/2$

# Neat way to find Confidence Intervals

Take  $\Delta \ln L = -\frac{1}{2}$  for 68% CL  
( $1\sigma$ )

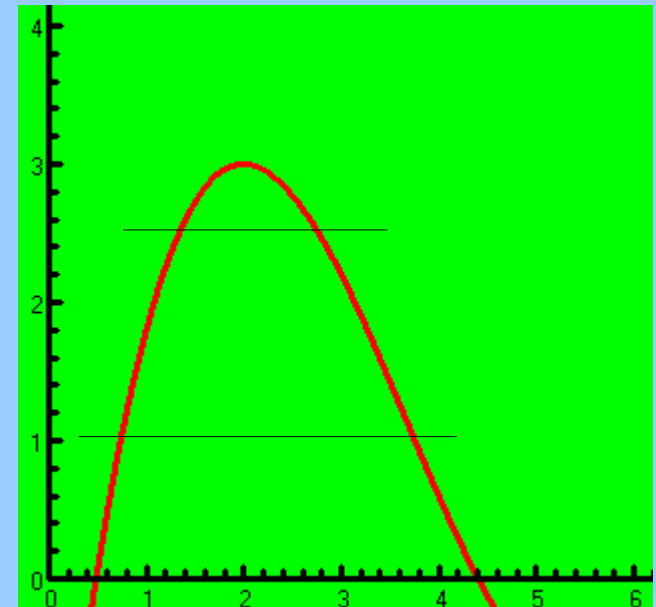
$\Delta \ln L = -2$  for 95.4% CL ( $2\sigma$ )

Or whatever you choose  
2-sided or 1-sided



# For finite N

- None of the above are true
- Never mind! We could transform from  $M \rightarrow M'$  where it was parabolic, find the limits, and transform back
- Would give  $\Delta \ln L = -\frac{1}{2}$  for 68% CL etc as before
- Hence asymmetric errors



*Everybody does this*

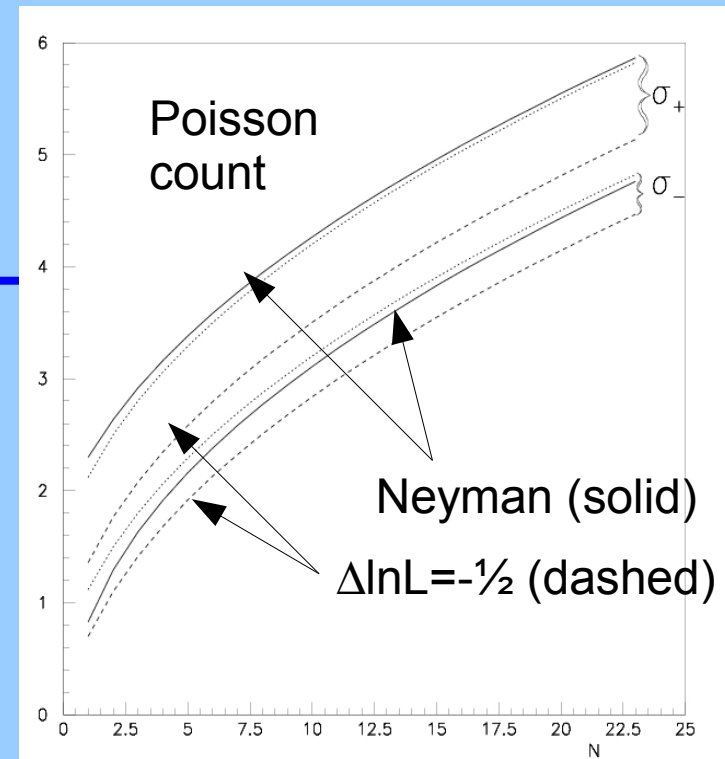
# Is it valid?

- Try and see with toy model (lifetime measurement) where we can do the Neyman construction
- For various numbers of measurements,  $N$ , normalised to unit lifetime
- There are some quite severe differences!

N	Exact		$\Delta \ln L = -\frac{1}{2}$	
	$\sigma_-$	$\sigma_+$	$\sigma_-$	$\sigma_+$
1	0.457	4.787	0.576	2.314
2	0.394	1.824	0.469	1.228
3	0.353	1.194	0.410	0.894
4	0.324	0.918	0.370	0.725
5	0.302	0.760	0.340	0.621
6	0.284	0.657	0.318	0.550
7	0.270	0.584	0.299	0.497
8	0.257	0.529	0.284	0.456
9	0.247	0.486	0.271	0.423
10	0.237	0.451	0.260	0.396
15	0.203	0.343	0.219	0.310
20	0.182	0.285	0.194	0.261
25	0.166	0.248	0.176	0.230

# Conclusions on $\Delta \ln L = -1/2$

- Is it valid? No
- We can make our curve a parabola, but we can't make the actual 2<sup>nd</sup> derivative equal its expectation value
- Differences in 2<sup>nd</sup> significant figure



- Will people stop using it? No
- But be careful when doing comparisons

Further details in NIM **550** 392 (2005)  
and PHYSTAT05

# 2: More dimensions

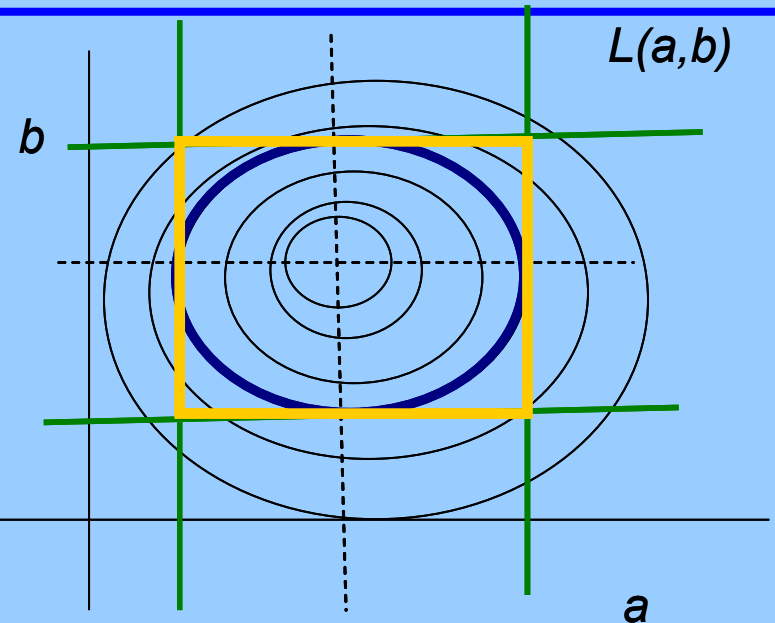
Suppose 2 uncorrelated parameters,  $a$  and  $b$

For fixed  $b$ ,  $\Delta \ln L = -\frac{1}{2}$  will give 68% CL region for  $a$

And likewise, fixing  $a$ , for  $b$

Confidence level for square is  $0.68^2 = 46\%$

Confidence level for ellipse (contour) is 39%



Jointly,  $\Delta \ln L = -\frac{1}{2}$  gives 39% CL region

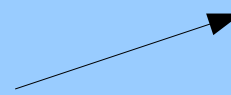
for 68% need  $\Delta \ln L = -1.15$



# More dimensions, other limits

- Useful to write
$$-2\Delta\ln L = \chi^2$$
- Careful! Given a multidimensional Gaussian,  $\ln L = -\chi^2/2$ . But  $-2\Delta\ln L$  obeys a  $\chi^2$  distribution only in the large N limit...
- Generalisation to correlated gaussians is straightforward
- Generalisation to more variables is straight forward. Need the larger  $\Delta\ln L$

Level is given by finding  $\chi^2$  such that  $P(\chi^2, N) = 1 - \text{CL}$



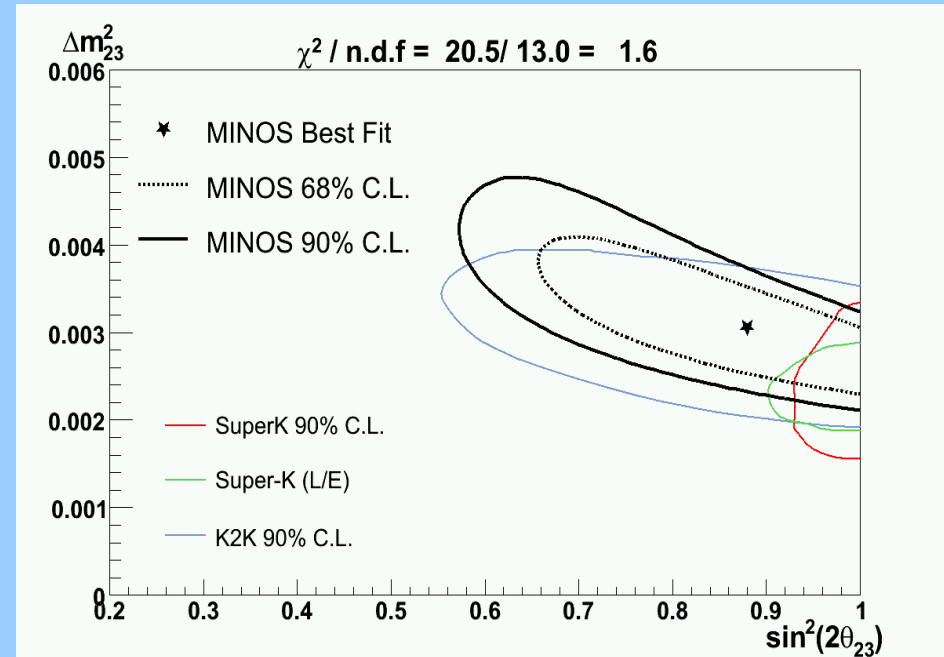
	68%	95%	99%
1	0.5	1.92	3.32
2	1.15	3.00	4.60
3	1.77	3.91	5.65

# Small N non-Gaussian measurements

No longer  
ellipses/ellipsoids

Use  $\Delta \ln L$  to define  
confidence regions,  
mapping out contours

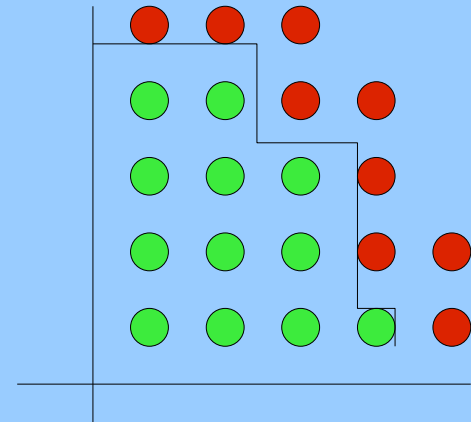
Probably not totally  
accurate, but universal



# What's the alternative?

## Toy Monte Carlo

- Have dataset
- Take point  $M$  in parameter space. Is it in or out of the 68% (or ...) contour?
- Find  $T = \ln L(R|\hat{M}) - \ln L(R|M)$   
clearly small  $T$  is 'good'
- Generate many MC sets of  $R$ , using  $M$
- How often is  $T_{MC} > T_{data}$  ?
- If more than 68%,  $M$  is in the contour



We are ordering the points by their value of  $T$  (the Likelihood Ratio) – almost contours but not quite

# 3: Nuisance parameters

## Systematic Errors

### Formalism

Model parameter M

Result R

Nuisance parameter(s) N

Likelihood is

- $L(M, N | R)$  from experiment
- $L'(N)$  about N

These are combined

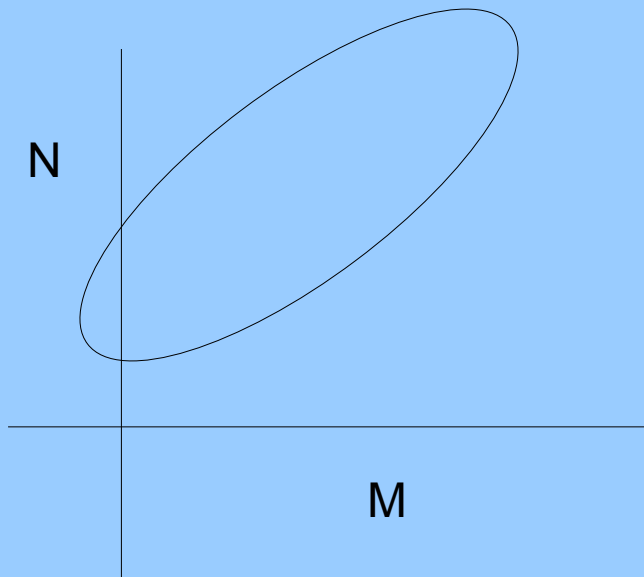
### Example: Poisson counting

- Source strength S
- R events seen
- Background b
- $b = b_0 \pm \sigma_b$
- Poisson(R, S+b)
- Gauss(b,  $b_0, \sigma_b$ )

$$e^{-(s+b)} \frac{(s+b)^R}{R!} \frac{1}{\sigma_b \sqrt{2\pi}} e^{-(b-b_0)^2 / 2\sigma_b^2}$$

# Approach 1

Quote joint CL contours for N and M



- This is a non-starter. Nobody cares about N. You're losing information about M. (N may be multidimensional)

# Approach 2

- Set  $N$  to central values to get quoted result for  $M$ . Then shift  $N$  up one sigma, repeat, and get (systematic) error on  $M$
- No theoretical justification
- Grossly over-estimates error on  $M$
- Still in use in some backward areas



# Approach 3

- Integrate out  $N$  to get  $L(M,R)$
- This can be done analytically or numerically
- Study  $L(M,R)$  and use  $\Delta \ln L = -\frac{1}{2}$  or equivalent



This is a frequentist/Bayesian hybrid. Acceptable (?) if the effects are small.

# Approach 4

- Profile Likelihood
- Use  $\hat{L}(R, M) = L(R, M, \hat{N})$
- Find maximum  $\hat{L}$
- See how it falls off and use  $\Delta \ln L = -1/2$  or equivalent, maximising by adjusting N as you step through M



Intuitively sensible  
Studies show it  
has reasonable  
properties



# 4: Justification (?) for using profile likelihood technique

Suppose  $\{M, N\}$  can be replaced by  $\{M, N'\}$  such that

$$L(R, M, N) = L(R, M) L'(R, N')$$

There are cases where this obviously works

There are cases where it obviously doesn't work

Assuming it does, the shape of  $L(R, M)$  can be found by fixing  $N'$ .

Can fix  $N'$  by taking the peak for given  $M$ , as  $L'(R, N')$  is independent of  $M$  and peak is always at the same  $N'$

# Profile Likelihood

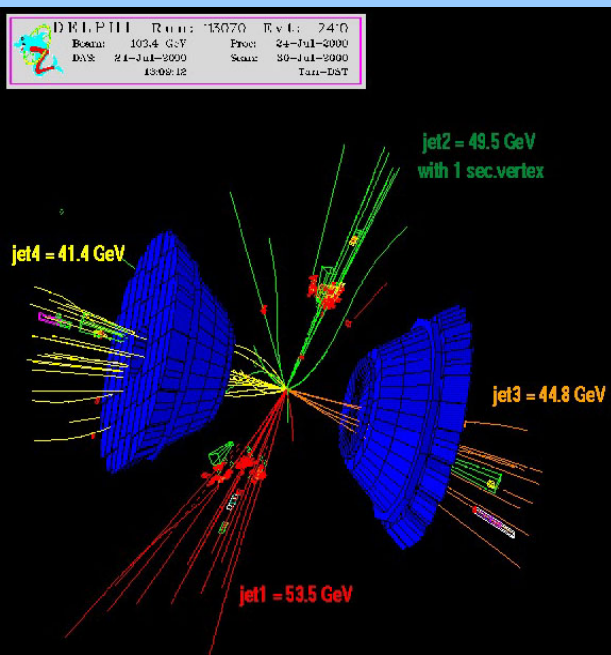
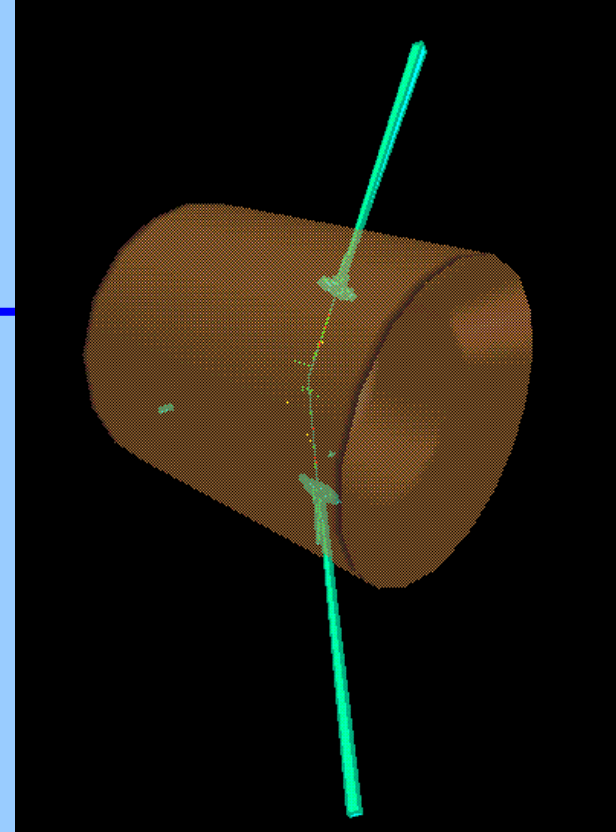
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- Provided by Minuit
- Available in ROOT as TRolke
- Use it!

# 5: The $CL_s$ Technique

Used for Higgs searches by the combined LEP experiments.

'Frequentist-motivated'



Different experiments selected events with varying degrees of Higgsishness

# Combining information

Define test-statistic  $Q$  which increases with signal  $s$ .  
Use Likelihood ratio  $L(R|M_H)/L(R|\text{no } H)$

Properties known (as function of  $M_H$ ) from Monte Carlo

Measure some  $Q_{\text{obs}}$

Define  $CL_b = P_b(Q \leq Q_{\text{obs}})$      $CL_{s+b} = P_{s+b}(Q \leq Q_{\text{obs}})$

$$CL_s = CL_{s+b} / CL_b$$

Treat this as a CL, even though it isn't. It therefore  
**overcovers.**

# Why divide?

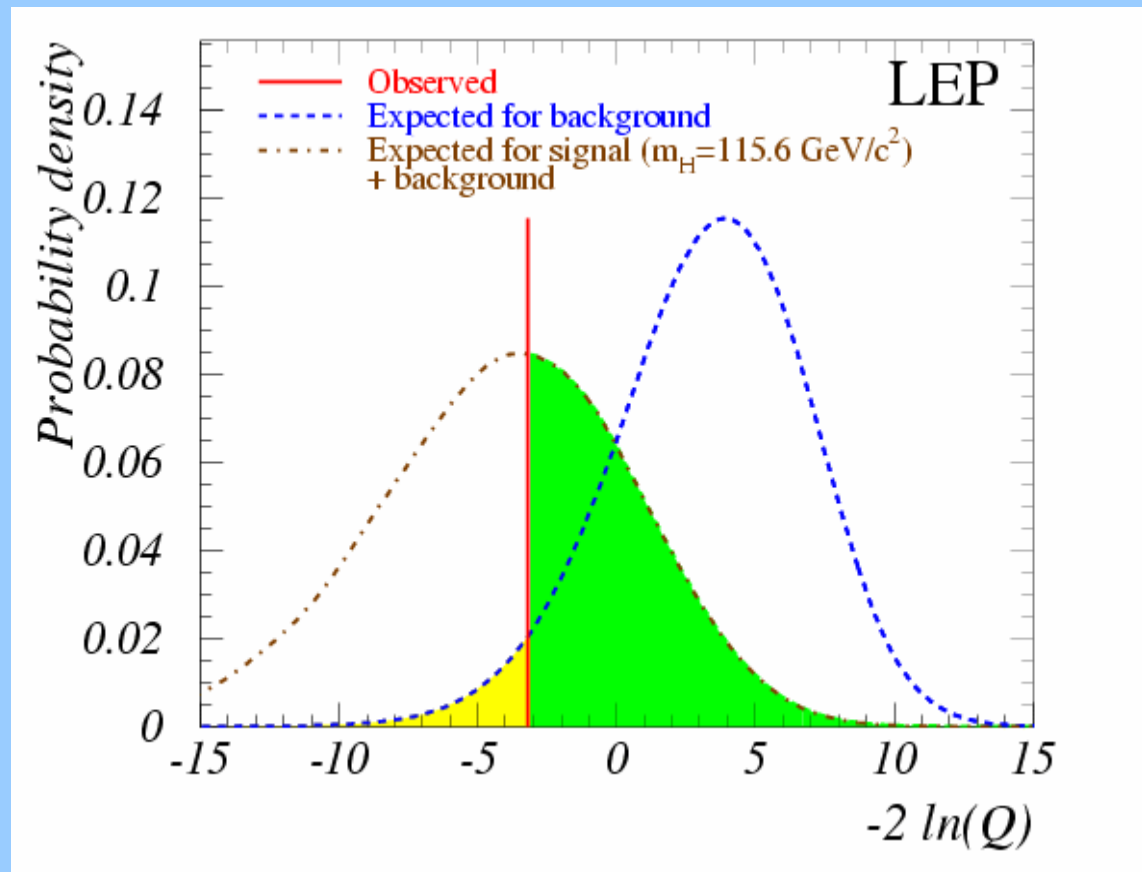
If you see a small number of events, you know that the background has a downward fluctuation. (In the limit of  $N=0$ , we know the background is zero)

This is like the Bayesian formula

$$\alpha = \frac{\sum_0^n e^{-(s+b)} (s+b)^r / r!}{\sum_0^n e^{-b} b^r / r!}$$

# What happens..

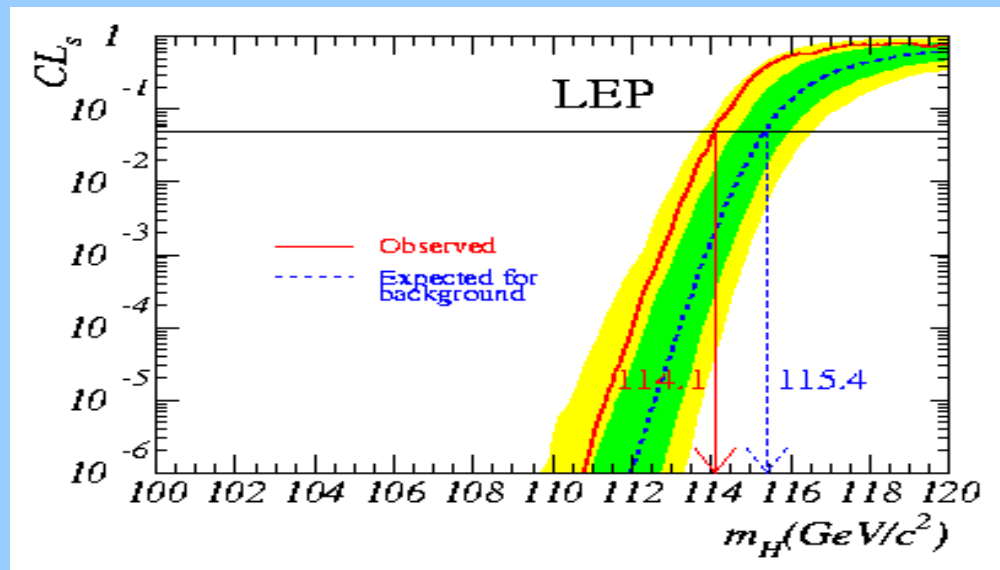
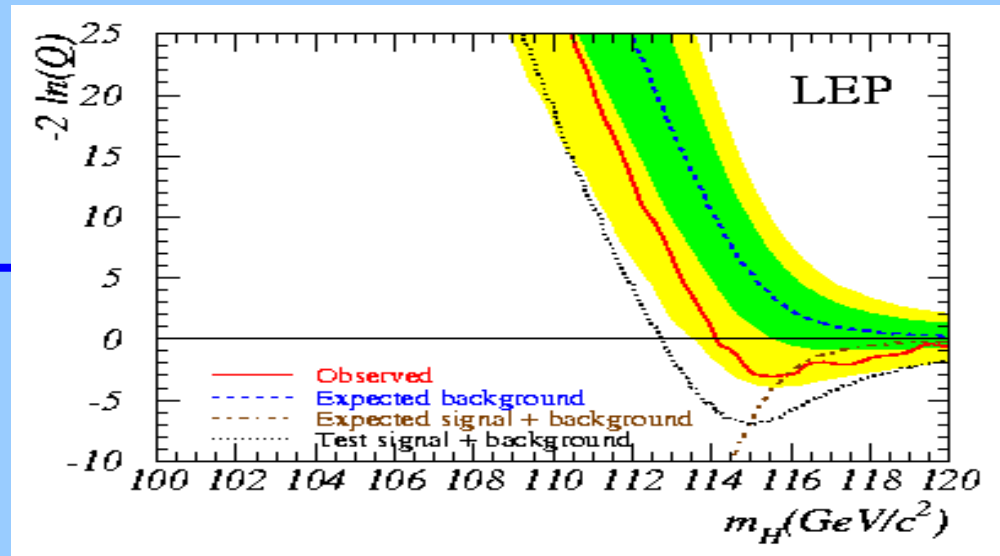
Yellow is  $1-CL_b$   
Green is  $CL_{s+b}$  for  
given  $m_H$



# Results

(as of 2002)

Rule out  $M_H$  up to  
114.1 GeV  
( $>114.1$  GeV @  
95%)



# Summary on $CL_s$

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Used for several searches at LEP and elsewhere

Adaptive and sensible.

Frequentist but 'behaves like  $P(\text{theory}|\text{Data})$ '

Well adapted to exclusion.

See Alex Read's talks at CERN and Durham workshops



# 6: The Banff Workshop outcome

Particle+statistics workshop in Banff, July 15-20 2006

- Task: given model

$$n = \text{Poisson}(\varepsilon s + b)$$

$$y = \text{Poisson}(tb)$$

$$z = \text{Poisson}(u\varepsilon)$$

$t, u$  known.  $n, y, z$  known

Put limit(s) on  $s$  at 90% and 99% CL.

# Many Models

- Bayesian
- Frequentist
- Hybrid
- ...

Part 1: 10,000 'experiments' have been generated

Participants to run their models and report results

Will be scored for coverage and shortness

Part 2: same again but with 10 separate channels per experiment (same  $s$ , different  $t, u, y, z$  and  $n$ )

Results to be announced in due course...

# 7: Further reading

- The Particle Data Book
- Textbooks by Glen Cowan, Louis Lyons, R.B.
- “Recommended Statistical Procedures for BaBar”  
BAD 318
- PHYSTAT proceedings (all Ed. Louis Lyons):
  - CERN 2000-05
  - Durham 2002 IPPP 02/39
  - SLAC 2003 SLAC-R-703
  - Oxford 2005 “Statistical problems in Particle Physics”, Imperial College Press (2006)