

# Merlin++

A flexible and feature-rich library for accelerator simulations

Roger Barlow  
Sam Tygier and Scott Rowan

The University of Huddersfield

13th November 2020



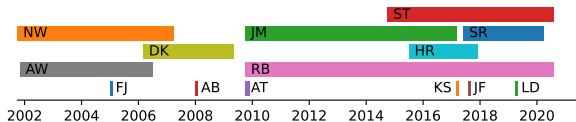
# What it's all about

- What is Merlin++?
  - A short history
  - Some examples
  - Where Merlin belongs
- The big picture
  - A library not a program
  - A truly Object Oriented program
  - Using the C++ compiler
  - Writing solid software
- Performance and Features
- Getting started

# What it's all about

## A short history

### History of Merlin++, formerly Merlin,



First developed at DESY, circa 2000, by Nick Walker for ILC studies

Extended by Andy Wolski to include linac and damping rings

Added Twiss parameter calculations and symplectic integrators

More features including wakefields, collimation and synchrotron radiation

Handed on to Manchester/Huddersfield in 2009

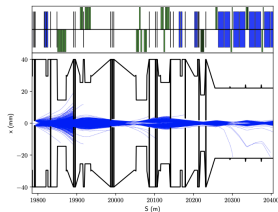
Developed including advanced scattering models and Hollow Electron Lens for LHC and HL-LHC collimation studies

Tidied up and renamed Merlin++

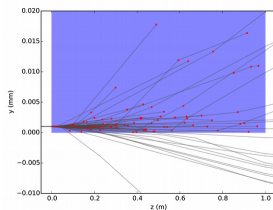
# What it's all about

Some examples

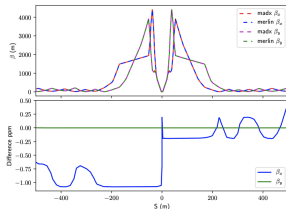
## Particles in the LHC collimators



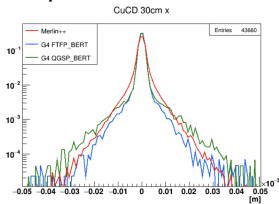
## Beam hitting the edge of a collimator



## $\beta$ functions around ATLAS from MAD and Merlin



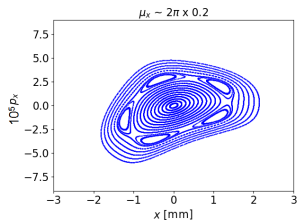
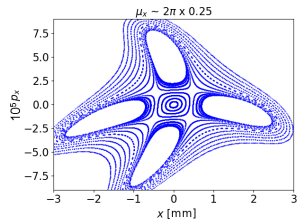
## Beam through a copper slab: Comparison with 2xGeant4



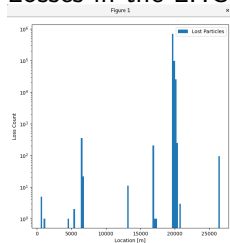
# What it's all about

Some more examples

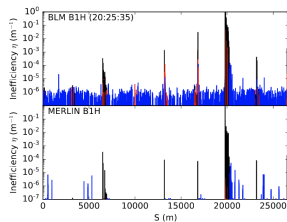
## Sextupole at the end of a FODO lattice



## Losses in the LHC



v=1.126-wd-y=148075



# What it's all about

Merlin, MAD and others

## MAD

Many more features

## Geant4

Does not do detailed collisions and cascades

Does do beam optics and particle bunches – and much faster

## FLUKA

Same as Geant4

## SixTrack

Similar purpose – but cleaner

## All the rest

Merlin++ is general purpose, specific aspects can be added

# The big picture

Why Merlin++ is a library, not a stand-alone not a program

## For

No need to write parser

Full flexibility of C++ language

User can do what they want with results. Developer does not have to anticipate

User can easily add their own classes

---

## Against

Have to compile program

User can do stupid things

## For the user

a library rather than a stand-alone program brings power and responsibility

## A lot more power

and only a little more responsibility

# The big picture

A full Object Oriented design

Accelerator (or beamline) comprises many components

Magnets (dipoles, quads, sextupoles), drifts, collimators...

Also applies to: particle distributions, trackers, scattering models ...

C-style solution

enumeration and switch

C++ solution

Inheritance: a quad is a magnet which is a component, and a particle is transported through it by its own member function

Extending Functionality

Makes it easy for the user to include a new process

Add child class with new feature - no need to change the core of Merlin++

If useful, can add to the library for other users



# The big picture

Using new C++ features

*You can write FORTRAN programs in any language*

Writing C++ code involves a continual battle not to write in C  
Design philosophy from the start was to **use** not just inheritance but all features of C++, e.g. Templates

Continue this philosophy as C++ develops (C++11, 14, 17...)

Some features of Merlin got included in later C++ versions. Discard and adapt new ones

## Random Numbers

Nick wrote Merlin with its own random number generator, as the standard that came with C++ at the time wasn't good enough for long-cycle simulations.

C++11 included a proper Mersenne Twister random number generator  
So we use it, and drop the old one

**For Merlin++, backwards compatibility is not an argument**

# The big picture

Writing high qualitycode

Good code is **fast**, **usable** and **sustainable** – code quality can be measured!

With help of CS colleagues (Colin Venters' group) , analysed Merlin

Scott Rowan et al, *Sustainability of the Merlin++ particle tracking code*,  
CHEP2018 <https://doi.org/10.1051/epjconf/201921405028>

Criteria e.g. from UK Software

Sustainability Institute

Some are just tickboxes: licensing

Some use tools: github, uncrustify,  
doxygen, cmake tests

Some are providing material:

website, tutorials, documentation

Some are more profound

e.g. meaningful names

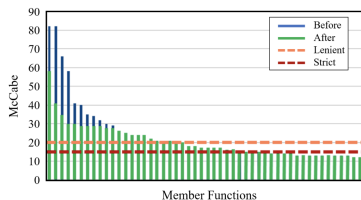
(PointInside() became

CheckWithinApertureBoundaries())

Sustainability Metric	Met Criteria	Initial Evaluation	Met Criteria	New Evaluation
Understandability	3/7	Unsatisfactory	6/7	Excellent
Documentation	3/19	Poor	14/19	Satisfactory
Buildability	3/9	Unsatisfactory	8/9	Excellent
Installability	7/14	Unsatisfactory	9/14	Satisfactory
Learnability	0/5	Poor	3/5	Satisfactory
Identity	3/7	Unsatisfactory	5/7	Satisfactory
Copyright	1/5	Poor	5/5	Excellent
Licensing	3/4	Satisfactory	4/4	Excellent
Governance	1/2	Unsatisfactory	2/2	Excellent
Community	1/11	Poor	6/11	Satisfactory
Accessibility	6/11	Satisfactory	8/11	Satisfactory
Testability	1/17	Poor	11/17	Satisfactory
Portability	10/16	Satisfactory	10/16	Satisfactory
Supportability	4/19	Poor	10/19	Satisfactory
Analysability	6/16	Unsatisfactory	13/16	Excellent
Changeability	3/10	Unsatisfactory	9/10	Excellent
Evolvability	0/3	Poor	2/3	Satisfactory
Interoperability	2/3	Satisfactory	3/3	Excellent

# Cleaning up the code

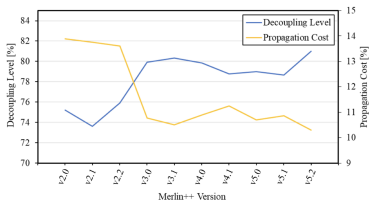
McCabe value: measures complexity (e.g. lots of `if` and `switch` statements means complex (=hard to read) code). Measured by `MetriCulator` package  
Cleaning up code also improves speed, through improving look-ahead (measured by `valgrind`)



## The bad guys:

Long Methods, Large Classes, Long Parameter Lists, Switch Statements, Alternative Classes With Different Interfaces, Parallel Inheritance Hierarchies, Duplicate Code, Dead code and Middle Man classes

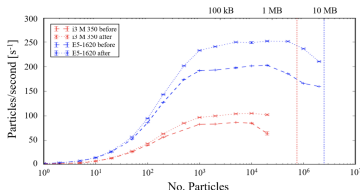
# Cleaning up the code - decoupling



Use ArchDiaDV8 tool to measure Propagation Cost (if you change one thing, how much else needs changing?) and Decoupling Level (are code modules independent?)

Overall figures generally good. Looking at history: got a lot better, then gradually worse, then better again thanks to Scott's clean-up efforts.

Not just cosmetic: changes also increase speed



# Implemented on

- linux (obviously). Ubuntu and Centos
- Windows because some people do use it
- MacOS because laptops can be useful as well as beautiful
- Raspberry Pi just because we can
- HTC condor for high-volume work. Random number seeding needed

Testing it on different architectures and operating systems has brought odd issues to light, and forced us to conform to standards

Runs standalone or from Eclipse

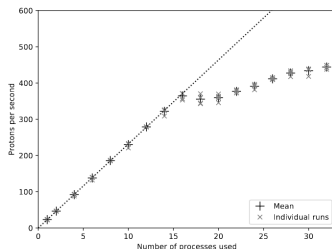
- Scattering: various models including the 'Practical Pomeron' implementation for elastic and diffractive scattering
- Synchrotron radiation - from a cooling point of view. Doesn't track the SR photons, though it could
- Spin tracking - haven't tested this but it's there
- High-order wakefields - geometric and resistive, for circular beampipes
- Hollow Electron Lens - Haroon Rafique's thesis
- Heavy Ions - Sam Tygier working on this for RHIC

# Performance

For a collimation study (horizontal halo) with scattering

- Tracking 10,000 particles for 10 LHC turns takes 110 secs on a desktop
- Tracking 1,000,000 particles for 100 LHC turns takes 13782 seconds (~ 4 hours)

Can use multiple cores with openmp (results shown for 16-core Xeon)







# Finally

We have come through a fairly major re-write and clean-up of Merlin++, now we want to widen the user base

So do give it a try...

and get in touch